



(Following Paper ID and Roll No. to be filled in your Answer Book)

PAPER ID : 121413

Roll No.

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B. Tech.

(SEM. IV) THEORY EXAMINATION, 2014-15
ELECTRIC MACHINE & AUTOMATIC CONTROL

Time : 3 Hours]

[Total Marks : 100

- 1 Attempt any four of the following : 4×5=20
- (a) Explain the different speed control methods used in a DC motor.
 - (b) Discuss conversion from 3 phase to 2 phase using Scott connection.
 - (c) Briefly enumerate the working of auto transformer with its merits, demerits.
 - (d) A 10 kva single phase 500/250 v transformer gave following test.

OC TEST	250 V	3A	200W
SC TEST	15V	30A	300W

Find efficiency and regulaton at full load 0.8 p.f. Lagging ?

- (e) Why series motor is never start on no load, also explain application of DC series and shunt motor.
- (f) Why starter is required in DC motor ? Explain different method of starting.
- 2 Attempt any two of the following : 10×2=20
- (a) (i) Explain the working principle of 3-phase induction motor. The rotor of induction motor cannot run at synchronous speed. Explain. Why ?
- (ii) 3- ϕ induction motor is wound for 4 poles and is supplied from 50 Hz system. Calculate
- (a) synchronous speed
- (b) rotor speed when slip is 4% and
- (c) rotor frequency when rotor runs at 600 rpm.
- (b) Explain the working of two phase servo motor and their application.
- (c) Explain the following :
- (i) Synchronizing of alternators
- (ii) V-curve of synchronous motor
- 3 Attempt any two of the following : 10×2=20
- (a) Compare open loop and closed loop system with suitable examples.

- (b) Obtain differential equation describing equivalent mechanical system of fig. 1 and draw the equivalent F-V analogy.

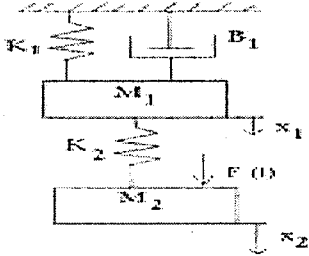


Fig. 1

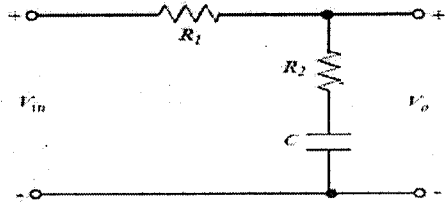


Fig. 2

- (c) What do you mean by Transfer Function; find out Transfer Function for Fig. 2 circuit.

4 Attempt any two of the following ; 10×2=20

- (a) Find out steady type error with unit step, ramp and parabolic input for

- (i) type zero
- (ii) type one
- (iii) type two system

- (b) (i) Explain bounded i/p bounded o/p stability criterion.
 (ii) Find stability condition for following characteristics equation

$$S^3 + 2ks^2 + (k+2)s + 4=0$$

- (c) Draw polar plot for $G(s) = K / (sA + 1)(sB+1)$ for unity feedback system, find Gain margin, phase margin.

5 Attempt any two of the following : 10×2=20

- (a) Draw bode plot and determine G.M., P.M., comment on stability.

$$G(s) H(s) = 16 (1+0.5s) / s^2 * (1+0.125s) * (1+0.1s)$$

- (b) Explain the Proportional, Derivative, Integral controller and write their advantages.

- (c) construct root locus for

$$G (s) H (s) = k/s* (s+4) * (s+5) \quad K > 0$$